





Pac-man as a learning agent



No a-priori information is available to the pac-man.

Enviroment

The environment (maze structure, ghosts and pills position) is not known to the pac-man \rightarrow environment identification. Large number of cells (\cong 30 x 32 = 960) and situations.

Reward is not known.

Ghosts behavior has also to be specified.

Agent: •Elements: State, Actions, Rewards, Value function. •Policy: Action = f(State). •Learning machinery.

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Pac-man learning

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Reinforcement learning is explored here. Fuzzy state definition allows managing the number of cells

Agent: •Elements: State, Actions, Rewards, Value function. •Policy: Action = f(State). •Learning machinery.

Environment: •Ghosts behavior. •Rewards

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The ghosts original behavior



In the original game design (*Susan Lammers: "Interview with Toru Iwatani, the designer of Pac-Man", Programmers at Work 1986*), the four ghosts had different personalities: **Ghost #1, chases directly after Pac- man. Ghost #2, positions himself a few dots in front of Pacman mouth** (if these two ghosts and the Pac-man are inside the same corridor a sandwich movement occurs). **Ghost #3 and #4, move randomly.**



Ghosts have to escape the Pac-man when the power pill is active.

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The more the game progresses the more the ghosts have to aim to the Pac-man.

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The ghosts behavior

At each step each ghost has to decide if moving north, south, east, west.

Shy behavior. The ghost moves away from the closest ghost This allows distributing the ghosts inside the maze. When the power pill is active, the ghosts tend to move as far as possible from the Pac-man. *The direction the maximize the increment of distance is chosen.* When ties are present, the Pac-man makes a randomized choice to avoid stereotyped behavior.





Random behavior. It chooses an admissible direction randomly.

Hunting behavior. The ghost chooses the direction of the minimum path to the Pacman. Minimum path has to be updated at each step as the Pac-man moves. The Floyd-Warshall algorithm is used to pre-compute the minimum path, distance between pairs of cells, for each cell of the maze, at game loading time.

Defence behavior. The ghosts go in the area in which the pills density is maximum. To this aim the maze is subdivided into nine partially overlapped areas: $\{0 - \frac{1}{2}; \frac{1}{4} - \frac{3}{4}; \frac{1}{2} - 1\}$ and the ghost aims to the center of the area waiting for the Pac-man.

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pill



Q-learning

Agent – the pacman

- State (fuzzy states) {s}
- Actions (Go to Pill, Go to Power Pill, Avoid Ghost, Go after Ghost) – {a}

Environment

- Related to enviroment, not known to the agent:
- Environment evolution: $s_{t+1} = g(s_t, a_t)$.
- = Reward: points gained $r_{t+1} = r(s_t, a_t, s_{t+1})$ in particular situations, e.g. Pill eaten, death)

The pacman optimizes through learning:

- Policy: $a_t = f(s_t)$
- Value function: $Q = Q(s_t, a_t)$

 $Q(s_{t},a_{t}) = Q(s_{t},a_{t}) + \alpha[r_{t+1} + \gamma \max_{a'} Q(s_{t+1}, a') - Q(s_{t},a_{t})]$



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Fuzzy State of the Pac-man

We measure the state:

- -The distance from the closest ghost, c1.
- The distance from the closest pill, c2.
- The distance from the closest power pill, c3.

Each element can fall in more than one state at each time step

We compute the membership to each fuzzy state s_i as:

 $\mu(s_j) = \frac{\sum_{i=1}^{3} m(c_i)}{2}$

Membership of each of the 3 components of the state. We update Variables taking into account fuzzyness of states.

With m(.) degree of membership of the measurement c_i to one of the fuzzy classes(small, medium, large) associated to each state variable (distance from closest ghost, closest pill, closest power pill).

More than one state can be active at each time step and the degrees of activity, $\mu(s_j)$ add to one.



Fuzzy Q-learning



$$Q(s_t^*, a_t) = \frac{1}{n} \sum_{i=1}^n \mu(s_{t,i}) q(s_{t,i}, a_t)$$

where q(.) is updated using Q-learning strategy as:

$$q(s_{t,i}, a_t) = q(s_{t,i}, a_t) + \alpha_{s,a} \left[r + \gamma \cdot \frac{1}{N} \max_{a'} Q(s_{t+1}, a') - q(s_{t,i}, a_t) \right]$$

$$\alpha \text{ is chosen as:} \qquad \alpha_{s,a} = \frac{1}{\sum_{0}^{\tau=t-1} \mu(s_{\tau,i})}$$

That is a natural extension of running average computation and it is inversely proportional to the cumulative membership of all the states active at that time step.ù

For each fuzzy state, a different optimal action for the next state s', is identified according to Q(s',a'). The action implemented in the one associated to the maximum fitness of the associated fuzzy state. A.A. 20 13/19

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Conclusion and further developments

- Highest score was around 4,500 and reported in *DeLooze*, *L.L.; Viner*, *W.R.;* "Fuzzy Q-learning in a nondeterministic environment: developing an intelligent Ms. Pac-Man agent", Computational Intelligence and Games, 2009. CIG 2009. pp.162-169, 7-10 Sept. 2009. We obtain here a large improvement in the score.
- Fuzzy approach has made RL approach feasible.
- We have only considered the bonus represented by power pills.
- A single scheme was used.
- Fuzzy classes boundaries were not optimized.
- A human player elaborates strategies both in chasing and escaping that are based on a global "view" of the game. This would require a much elaborate learning machinery than "simple" RL.
- Here is the Pac-man learning live....

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